Lecture 3 Probability - Part 2

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1 Common Continuous Distributions - Univariate

- Gaussian Distribution
- Degenerate PDFs
- Student's t Distribution
- Laplace Distribution
- Gamma Distribution
- Beta Distribution
- Pareto Distribution

- Joint Probability Distributions
- Joint CDF and PDF
- Marginal PDF
- Conditional PDF and Independence
- Covariance and Correlation
- Correlation and Independence
- Common Multivariate Distributions

Common Continuous Distributions - Univariate

Gaussian Distribution

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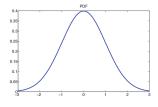
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- Marginal PDF
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Gaussian (Normal) Distribution

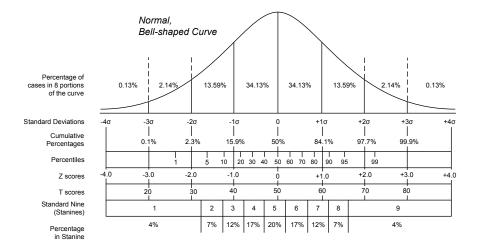
- X is a continuous RV with values $x \in \mathbb{R}$
- $X \sim \mathcal{N}(\mu, \sigma^2)$, i.e. X has a Gaussian distribution or normal distribution

$$\mathcal{N}(x|\mu,\sigma^2) \triangleq \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2} \qquad (= P_X(X=x))$$

- mean $\mathbb{E}[X] = \mu$
- mode μ
- variance var $[X] = \sigma^2$
- precision $\lambda = \frac{1}{\sigma^2}$
- $(\mu 2\sigma, \mu + 2\sigma)$ is the approx 95% interval
- $(\mu 3\sigma, \mu + 3\sigma)$ is the approx. 99.7% interval



Gaussian (Normal) Distribution



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Gaussian (Normal) Distribution

why Gaussian distribution is the most widely used in statistics?

- **(**) easy to interpret: just two parameters $\boldsymbol{\theta} = (\mu, \sigma^2)$
- entral limit theorem: the sum of independent random variables has an approximately Gaussian distribution
- (3) least number of assumptions (maximum entropy) subject to constraints of having mean = μ and variance = σ^2
- simple mathematical form, easy to manipulate and implement

homework: show that

$$\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2} dx = 1$$

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Degenerate PDFs

- X is a continuous RV with values $x \in \mathbb{R}$
- consider a Gaussian distribution with $\sigma^2
 ightarrow 0$

$$\delta(x-\mu) \triangleq \lim_{\sigma^2 \to 0} \mathcal{N}(x|\mu, \sigma^2)$$

• $\delta(x)$ is the **Dirac delta function**, with

$$\delta(x) = \begin{cases} \infty & \text{if } x = 0\\ 0 & \text{if } x \neq 0 \end{cases}$$

• one has
$$\int\limits_{-\infty}^{\infty} \delta(x) dx = 1$$

$$(\lim_{\sigma^2 \to 0} \int_{-\infty}^{\infty} \mathcal{N}(x|\mu, \sigma^2) dx = 1)$$

sifting property

$$\int_{-\infty}^{\infty} f(x)\delta(x-\mu)dx = f(\mu)$$

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- X is a continuous RV with values $x \in \mathbb{R}$
- $X \sim \mathcal{T}(\mu, \sigma^2, \nu)$, i.e. X has a Student's t distribution

$$\mathcal{T}(x|\mu,\sigma^2,\nu) \propto \left[1 + \frac{1}{\nu} \left(\frac{x-\mu}{\sigma}\right)^2\right]^{-\left(\frac{\nu+1}{2}\right)} \qquad (= P_X(X=x))$$

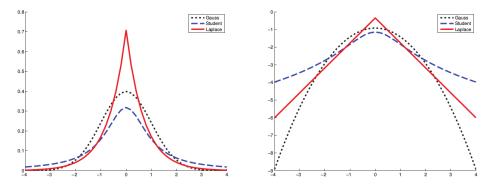
- scale parameter $\sigma^2 > 0$
- degrees of freedom ν
- mean $\mathbb{E}[X] = \mu$ defined if $\nu > 1$
- mode μ
- variance var $[X] = \frac{\nu \sigma^2}{(\nu 2)}$ defined if $\nu > 2$

Student's t Distribution

• a comparison of $\mathcal{N}(0,1), \ \mathcal{T}(0,1,1)$ and $\mathsf{Lap}(0,1,\sqrt{2})$

PDF

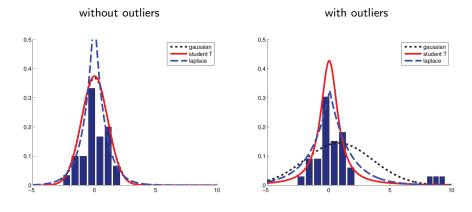
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Student's t Distribution

why should we use the Student distribution?

• it is less sensitive to outliers than the Gaussian distribution



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Laplace Distribution

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Laplace Distribution

• X is a continuous RV with values $x \in \mathbb{R}$

• X ~ Lap(µ, b), i.e. X has a Laplace distribution

$$Lap(x|\mu, b) \triangleq \frac{1}{2b} exp\left(-\frac{|x-\mu|}{b}\right) \qquad (= P_X(X=x))$$

- scale parameter b > 0
- mean $\mathbb{E}[X] = \mu$
- mode μ
- variance var[X] = 2b²

compared to Gaussian distribution, Laplace distribution

- is more rubust to outliers (see above)
- puts more probability density at μ (see above)

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Gamma Distribution

- X is a continuous RV with values $x \in \mathbb{R}^+$ (x > 0)
- $X \sim Ga(a, b)$, i.e. X has a gamma distribution

$$Ga(x|a,b) \triangleq \frac{b^a}{\Gamma(a)} x^{a-1} e^{-xb} \qquad (= P_X(X=x))$$

- shape *a* > 0
- rate b > 0
- the gamma function is

$$\Gamma(x) riangleq \int\limits_{-\infty}^{\infty} u^{x-1} e^{-u} du$$

where $\Gamma(x) = (x-1)!$ for $x \in \mathbb{N}$ and $\Gamma(1) = 1$

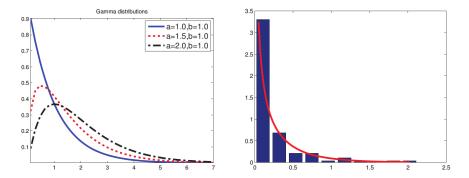
- mean $\mathbb{E}[X] = \frac{a}{b}$
- mode $\frac{a-1}{b}$
- variance var $[X] = \frac{a}{b^2}$

N.B.: there are several distributions which are just special cases of the Gamma (e.g. exponential, Erlang, Chi-squared)

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Gamma Distribution

- some Ga(a, b = 1) distributions
- right: an empirical PDF of some rainfall data



- X is a continuous RV with values $x \in \mathbb{R}^+$ (x > 0)
- if $X \sim Ga(a, b)$, i.e. $\frac{1}{x} \sim IG(a, b)$
- IG(a, b) is the inverse gamma distribution

$$\mathsf{IG}(x|a,b) \triangleq \frac{b^a}{\Gamma(a)} x^{-(a+1)} e^{-b/x} \qquad (= P_X(X=x))$$

- mean $\mathbb{E}[X] = \frac{b}{a-1}$ (defined if a > 1)
- mode $\frac{b}{a+1}$
- variance var[X] = $\frac{b^2}{(a-1)^2(a-2)}$

- (defined if a > 2)

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Pareto Distribution

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- X is a continuous RV with values $x \in [0, 1]$
- $X \sim \text{Beta}(a, b)$, i.e. X has a **beta distribution**

Beta
$$(x|a,b) = \frac{1}{B(a,b)} x^{a-1} (1-x)^{b-1}$$
 (= $P_X(X=x)$)

- requirements: a > 0 and b > 0
- the beta function is

$$B(a,b) riangleq rac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}$$

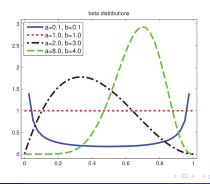
- mean $\mathbb{E}[X] = \frac{a}{a+b}$
- mode $\frac{a-1}{a+b-2}$
- variance var[X] = $\frac{ab}{(a+b)^2(a+b+1)}$

Beta Distribution

beta distribution

Beta
$$(x|a,b) = \frac{1}{B(a,b)} x^{a-1} (1-x)^{b-1}$$
 (= $P_X(X=x)$)

- requirements: a > 0 and b > 0
- if a = b = 1 then $\mathsf{Beta}(x|1,1) = \mathit{Unif}(x|1,1)$ in the interval $[0,1] \subset \mathbb{R}$
- this distribution can be used to represent a prior on a probability value to be estimated



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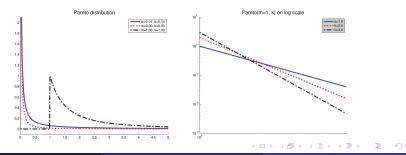
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Pareto Distribution

- X is a continuous RV with values $x \in \mathbb{R}^+$ (x > 0)
- X ~ Pareto(k, m), i.e. X has a Pareto distribution

$$\mathsf{Pareto}(x|k,m) = km^k x^{-(k+1)}\mathbb{I}(x \ge m) \qquad (= P_X(X = x))$$

- as $k \to \infty$ the distribution approaches $\delta(x)$
- mean $\mathbb{E}[X] = \frac{km}{k-1}$ (defined for k > 1)
- mode m
- variance var[X] = $\frac{m^2k}{(k-1)^2(k-2)}$
- this distribution is particular useful for its long tail



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- consider an ensemble of RVs X₁, ..., X_D
- we can define a new RV $\mathbf{X} \triangleq (X_1, ..., X_D)^T$
- we are now interested in modeling the stochastic relationship between $X_1, ..., X_D$
- in this case $\mathbf{x} = (x_1, ..., x_D)^T \in \mathbb{R}^D$ denotes a particular value (instance) of \mathbf{X}

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Joint Cumulative Distribution Function Definition

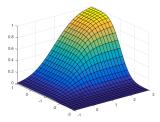
given a continuous RV **X** with values $\mathbf{x} \in \mathbb{R}^{D}$

Cumulative Distribution Function (CDF)

$$F(\mathbf{x}) = F(x_1, ..., x_D) \triangleq P_{\mathbf{X}}(\mathbf{X} \leq \mathbf{x}) = P_{\mathbf{X}}(X_1 \leq x_1, ..., X_D \leq x_D)$$

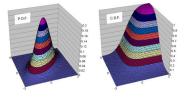
- properties:
 - $0 < F(\mathbf{x}) < 1$ • $F(x_1, ..., x_i, ..., x_D) \leq F(x_1, ..., x_i + \Delta x_j, ..., x_D)$ with $\Delta x_j > 0$ • $\lim_{\Delta x_i \to 0^+} F(x_1, ..., x_j + \Delta x_j, ..., x_D) = F(x_1, ..., x_j, ..., x_D)$ (right-continuity)

 - $F(-\infty,...,-\infty)=0$
 - $F(+\infty, ..., +\infty) = 1$



Joint Probability Density Function Definitions

given a continuous RV **X** with values $\mathbf{x} \in \mathbb{R}^{D}$



• Probability Density Function (PDF)

$$p(\mathbf{x}) = p(x_1, ..., x_D) \triangleq \frac{\partial^D F}{\partial x_1, ..., \partial x_D}$$

we assume the above partial derivative of F exists

operties:

•
$$F(\mathbf{x}) = P_{\mathbf{X}}(\mathbf{X} \le \mathbf{x}) = \int_{-\infty}^{x_1} \dots \int_{-\infty}^{x_D} p(\xi_1, \dots, \xi_D) d\xi_1 \dots d\xi_D$$

• $P_{\mathbf{X}}(\mathbf{x} < \mathbf{X} \le \mathbf{x} + d\mathbf{x}) \approx p(\mathbf{x}) dx_1 \dots dx_D = p(\mathbf{x}) d\mathbf{x}$
• $P_{\mathbf{X}}(\mathbf{a} < \mathbf{X} \le \mathbf{b}) = \int_{a_1}^{b_1} \dots \int_{a_D}^{b_D} p(\mathbf{x}) dx_1 \dots dx_D$

N.B.: $p(\mathbf{x})$ acts as a density in the above computations

for a discrete RV \boldsymbol{X} we have instead

- Probability Mass Function (PMF): $p(\mathbf{x}) \triangleq P_{\mathbf{X}}(\mathbf{X} = \mathbf{x})$
- in the above properties we can remove dx and replace integrals with sums
- the CDF can be defined as

$$F(\mathbf{x}) \triangleq P_{\mathbf{X}}(\mathbf{X} \leq \mathbf{x}) = \sum_{\boldsymbol{\xi}_i \leq \mathbf{x}} p(\boldsymbol{\xi}_i)$$

reconsider

1 $F(\mathbf{x}) = P_{\mathbf{X}}(\mathbf{X} \le \mathbf{x}) = \int_{-\infty}^{x_1} \dots \int_{-\infty}^{x_D} p(\xi_1, \dots, \xi_D) d\xi_1 \dots d\xi_D$

- the first implies $\int_{-\infty} ... \int_{-\infty}^{\infty} p(\mathbf{x}) d\mathbf{x} = 1$ (consider $(x_1, ..., x_D) \to (\infty, ..., \infty)$))
- the second implies $p(\mathbf{x}) \geq 0$ for all $\mathbf{x} \in \mathbb{R}^D$
- it is possible that $p(\mathbf{x}) > 1$ for some $\mathbf{x} \in \mathbb{R}^D$

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Joint PDF Marginal PDF

suppose we want the PDF of $\mathbf{Q} \triangleq (X_1, X_2, ..., X_{D-1})^T$ (we don't care about X_D)

- $F_{\mathbf{Q}}(\mathbf{q}) = P_{\mathbf{Q}}(\mathbf{Q} \le \mathbf{q}) = P_{\mathbf{X}}(\mathbf{X} \le (\mathbf{q}, \infty)^T)$ $(X_D \text{ can take any value in } (-\infty, \infty))$
- $P_{\mathbf{X}}(\mathbf{X} \leq (\mathbf{q}, \infty)) = \int_{-\infty}^{x_1} \dots \int_{-\infty}^{x_{D-1}} \int_{-\infty}^{\infty} p_{\mathbf{X}}(\mathbf{x}) dx_1 \dots dx_{D-1} dx_D = \int_{-\infty}^{x_1} \dots \int_{-\infty}^{x_{D-1}} \left(\int_{-\infty}^{\infty} p_{\mathbf{X}}(\mathbf{x}) dx_D \right) dx_1 \dots dx_{D-1}$

hence we can define the marginal PDF

$$p_{\mathbf{Q}}(\mathbf{q}) = p_{\mathbf{Q}}(x_1, ..., x_{D-1}) \triangleq \int_{-\infty}^{\infty} p_{\mathbf{X}}(x_1, ..., x_D) dx_D$$

and one has

$$F_{\mathbf{Q}}(\mathbf{q}) = F_{\mathbf{Q}}(x_1, ..., x_{D-1}) = \int_{-\infty}^{x_1} ... \int_{-\infty}^{x_{D-1}} p_{\mathbf{Q}}(\mathbf{q}) dx_1 ... dx_{D-1}$$

- the above procedure can be also used to marginalize more variables
- the above procedure can be used for obtaining a **marginal PMF** for discrete variables by removing the *dx* and replacing integrals with sums, i.e.

$$p_{\mathbf{Q}}(\mathbf{q}) = p_{\mathbf{Q}}(x_1, x_2, ..., x_{D-1}) \triangleq \sum_{\mathbf{x}_D} p_{\mathbf{X}}(x_1, x_2, ..., x_D)$$

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- Gamma Distribution
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- Pareto Distribution

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- Joint CDF and PDF
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Joint PDF Conditional PDF and Independence

suppose we want the PDF of $\mathbf{Q} \triangleq (X_1, X_2, ..., X_{D-1})^T$ given $X_D = x_D$

•
$$P_{\mathbf{Q}|X_D}(\mathbf{q} < \mathbf{Q} \le \mathbf{q} + d\mathbf{q} \mid x_D < X_D \le x_D + dx_D) = \frac{P_{\mathbf{x}}(\mathbf{x} < \mathbf{X} \le \mathbf{x} + d\mathbf{x})}{P_{x_D}(x_D < X_D \le x_D + dx_D)}$$

•
$$P_{\mathbf{X}}(\mathbf{x} < \mathbf{X} \le \mathbf{x} + d\mathbf{x}) \approx p_{\mathbf{X}}(\mathbf{x}) dx_1 ... dx_D$$

•
$$P_{X_D}(x_D < X_D \leq x_D + dx_D) \approx p_{X_D}(x_D) dx_D$$

• hence
$$P_{\mathbf{Q}|X_D}(\mathbf{q} < \mathbf{Q} \le \mathbf{q} + d\mathbf{q} \mid x_D < X_D \le x_D + dx_D) \approx \frac{p_{\mathbf{X}}(\mathbf{x})}{p_{X_D}(x_D)} dx_1 \dots dx_{D-1}$$

we can define the conditional PDF

$$p_{\mathbf{Q}|X_D}(\mathbf{q}|x_D) = p_{\mathbf{Q}|X_D}(x_1, ..., x_{D-1}|x_D) \triangleq \frac{p_{\mathbf{X}}(\mathbf{x})}{p_{X_D}(x_D)}$$

- **Q** and X_D are independent $\iff p_X(\mathbf{x}) = p_Q(\mathbf{q})p_{x_D}(x_D)$
- if **Q** and X_D are independent then $p_{\mathbf{Q}|X_D}(\mathbf{q}|x_D) = p_{\mathbf{Q}}(\mathbf{q})$
- the above definitions can be generalized to define the conditional PDF w.r.t. more variables

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- Beta Distribution
- Pareto Distribution

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Covariance

• covariance of two RVs X and Y

 $\operatorname{cov}[X,Y] \triangleq \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y] \qquad (= \operatorname{cov}[Y,X])$

• if $\mathbf{x} \in \mathbb{R}^d$, the mean value is

$$\mathbb{E}[\mathbf{x}] \triangleq \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} \mathbf{x} p(\mathbf{x}) d\mathbf{x} = \begin{bmatrix} \mathbb{E}[x_1] \\ \vdots \\ \mathbb{E}[x_D] \end{bmatrix} \in \mathbb{R}^D$$

• if $\mathbf{x} \in \mathbb{R}^d$, the covariance matrix is

$$\operatorname{cov}[\mathbf{x}] \triangleq \mathbb{E}[(\mathbf{x} - \mathbb{E}[\mathbf{x}])(\mathbf{x} - \mathbb{E}[\mathbf{x}])^{T}] =$$

$$= \begin{bmatrix} \operatorname{var}[X_1] & \operatorname{cov}[X_1, X_2] & \dots & \operatorname{cov}[X_1, X_d] \\ \operatorname{cov}[X_2, X_1] & \operatorname{var}[X_2] & \dots & \operatorname{cov}[X_2, X_d] \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{cov}[X_d, X_1] & \operatorname{cov}[X_d, X_2] & \dots & \operatorname{var}[X_d] \end{bmatrix} \in \mathbb{R}^{D \times D}$$

$$\bullet \quad \text{N.B.: } \operatorname{cov}[\mathbf{x}] = \operatorname{cov}[\mathbf{x}]^T \text{ and } \operatorname{cov}[\mathbf{x}] \ge 0$$

Correlation

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• correlation coefficient of two RVs X and Y

$$\operatorname{corr}[X, Y] \triangleq \frac{\operatorname{cov}[X, Y]}{\sqrt{\operatorname{var}[X] \operatorname{var}[Y]}}$$

it can be to shown that
$$0 \le \operatorname{corr}[X, Y] \le 1$$
 (homework¹)
 $\operatorname{corr}[X, Y] = 0 \iff \operatorname{cov}[X, Y] = 0$

• if $\mathbf{x} \in \mathbb{R}^d$, its correlation matrix is

$$\operatorname{corr}[\mathbf{x}] \triangleq \begin{bmatrix} \operatorname{corr}[X_1, X_1] & \operatorname{corr}[X_1, X_2] & \dots & \operatorname{corr}[X_1, X_d] \\ \operatorname{corr}[X_2, X_1] & \operatorname{corr}[X_2, X_2] & \dots & \operatorname{corr}[X_2, X_d] \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{corr}[X_d, X_1] & \operatorname{corr}[X_d, X_2] & \dots & \operatorname{corr}[X_d, X_d] \end{bmatrix} \in \mathbb{R}^{D \times D}$$

• N.B.: $\operatorname{corr}[\mathbf{x}] = \operatorname{corr}[\mathbf{x}]^T$

¹use the fact that $\left(\int f(t)g(t)dt\right)^2 \leq \int f^2dt \int g^2dt$

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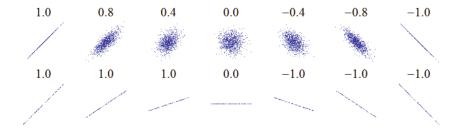
• Common Multivariate Distributions

Correlation and Independence

• **Property 1**: there is a linear relationship between X and Y iff corr[X, Y] = 1, i.e.

$$\operatorname{corr}[X, Y] = 1 \iff Y = aX + b$$

• the correlation coefficient represents a degree of linear relationship



Correlation and Independence

Property 2: if X and Y are independent (p(X, Y) = p(X)p(Y)) then cov[X, Y] = 0 and corr[X, Y] = 0, i.e. (homework)

$$X \perp Y \Longrightarrow \operatorname{corr}[X, Y] = 0$$

• Property 3:

$$\operatorname{corr}[X,Y] = 0 \Longrightarrow X \perp Y$$

example: with $X \sim U(-1,1)$ and $Y = X^2$ (quadratic dependency) one has corr[X, Y] = 0 (homework)

 other examples where corr[X, Y] = 0 but there is a cleare dependence between X and Y



• a more general measure of dependence is the mutual information

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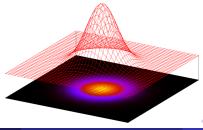
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- Covariance and Correlation
- Correlation and Independence
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Multivariate Gaussian (Normal) Distribution

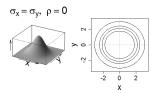
- **X** is a continuous RV with values $\mathbf{x} \in \mathbb{R}^{D}$
- X ~ $\mathcal{N}(\mu, \Sigma)$, i.e. X has a Multivariate Normal distribution (MVN) or multivariate Gaussian

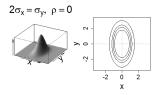
$$\mathcal{N}(\mathsf{x}|oldsymbol{\mu},oldsymbol{\Sigma}) riangleq rac{1}{(2\pi)^{D/2}|oldsymbol{\Sigma}|^{1/2}} \mathsf{exp}igg[-rac{1}{2}(\mathsf{x}-oldsymbol{\mu})^Toldsymbol{\Sigma}^{-1}(\mathsf{x}-oldsymbol{\mu})igg]$$

- mean: $\mathbb{E}[\mathsf{x}] = \mu$
- mode: μ
- covariance matrix: $\operatorname{cov}[\mathbf{x}] = \mathbf{\Sigma} \in \mathbb{R}^{D \times D}$ where $\mathbf{\Sigma} = \mathbf{\Sigma}^{T}$ and $\mathbf{\Sigma} \geq 0$
- precision matrix: $\mathbf{\Lambda} \triangleq \mathbf{\Sigma}^{-1}$
- spherical isotropic covariance with $\mathbf{\Sigma} = \sigma^2 \mathbf{I}_D$

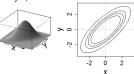


Multivariate Gaussian (Normal) Distribution Bivariate Normal





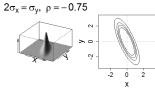
 $\sigma_x = \sigma_y, \ \rho = 0.75$







 $\sigma_{\chi} = \sigma_{y}, \ \rho = -0.75$



- **X** is a continuous RV with values $\mathbf{x} \in \mathbb{R}^{D}$
- $X \sim \mathcal{T}(\mu, \Sigma, \nu)$, i.e. X has a Multivariate Student t distribution

$$\mathcal{T}(\mathbf{x}|\boldsymbol{\mu},\boldsymbol{\Sigma},\nu) \triangleq \frac{\Gamma(\nu/2+D/2)}{\Gamma(\nu/2)} \frac{|\boldsymbol{\Sigma}|^{-1/2}}{\nu^{D/2}\pi^{D/2}} \left[1 + \frac{1}{\nu}(\mathbf{x}-\boldsymbol{\mu})^{\mathsf{T}}\boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})\right]^{-(\frac{\nu+D}{2})}$$

- mean: $\mathbb{E}[x] = \mu$
- mode: μ
- $\Sigma = \Sigma^T$ is now called the scale matrix
- covariance matrix: $\operatorname{cov}[\mathbf{x}] = \frac{\nu}{\nu-2} \boldsymbol{\Sigma}$
- N.B.: this distribution is similar to MVN but it's **more robust** w.r.t outliers due to its fatter tails (see the previous slides about univariate Student t distribution)

Dirichlet Distribution

- **X** is a continuous RV with values $\mathbf{x} \in S_K$
- probability simplex $S_{\mathcal{K}} \triangleq \{ \mathbf{x} \in \mathbb{R}^{\mathcal{K}} : 0 \le x_i \le 1, \sum_{i=1}^{\mathcal{K}} x_i = 1 \}$
- the vector $\mathbf{x} = (x_1, ..., x_K)$ can be used to represent a set of K probabilities
- $X \sim \text{Dir}(\alpha)$, i.e. X has a **Dirichlet** distribution

$$\mathsf{Dir}(\mathbf{x}|\boldsymbol{\alpha}) \triangleq \frac{1}{B(\boldsymbol{\alpha})} \prod_{i=1}^{K} x_i^{\alpha_i - 1} \mathbb{I}(\mathbf{x} \in S_{\mathcal{K}})$$

where $\alpha \in \mathbb{R}^{K}$ and $B(\alpha)$ is a generalization of the beta function to K variables²

$$B(\boldsymbol{\alpha}) = B(\alpha_1, ..., \alpha_K) \triangleq \frac{\prod_{i=1}^{K} \Gamma(\alpha_i)}{\Gamma(\alpha_0)}$$

• $\alpha_0 = \sum_{i=1}^{K} \alpha_i$ • $\mathbb{E}[x_k] = \frac{\alpha_k}{\alpha_0}$, mode $[x_k] = \frac{\alpha_k - 1}{\alpha_0 - K}$, $\operatorname{var}[x_k] = \frac{\alpha_k (\alpha_0 - \alpha_K)}{\alpha_0^2 (\alpha_0 + 1)}$

• N.B.: this distribution is a multivariate generalization of the beta distribution

²see the slide about the gamma distribution for the definition of $\Gamma(\alpha)$ \equiv \geq $\sim \sim \sim$ Luigi Freda ("La Sapienza" University) Lecture 3 October 19, 2016 45 / 46 • Kevin Murphy's book

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