Lecture 3 Probability - Part 2

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- Common Continuous Distributions Univariate
 - Gaussian Distribution
 - Degenerate PDFs
 - Student's t Distribution
 - Laplace Distribution
 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
 - Joint Probability Distributions Multivariate
 - Joint Probability Distributions
 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
 - Correlation and Independence
 - Common Multivariate Distributions

- Common Continuous Distributions Univariate
 - Gaussian Distribution
 - Degenerate PDFs
 - Student's t Distribution
 - Laplace Distribution
 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
 - Joint Probability Distributions
 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
 - Correlation and Independence
 - Common Multivariate Distributions

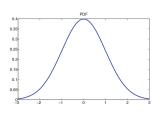


Gaussian (Normal) Distribution

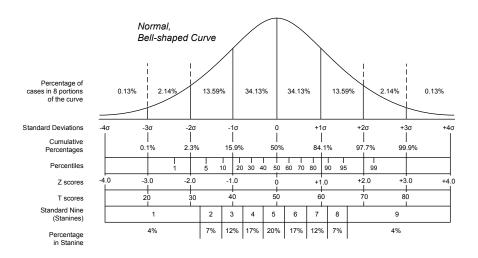
- X is a continuous RV with values $x \in \mathbb{R}$
- $X \sim \mathcal{N}(\mu, \sigma^2)$, i.e. X has a Gaussian distribution or normal distribution

$$\mathcal{N}(x|\mu,\sigma^2) \triangleq \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$$
 (= $P_X(X=x)$)

- mean $\mathbb{E}[X] = \mu$
- ullet mode μ
- variance $var[X] = \sigma^2$
- precision $\lambda = \frac{1}{\sigma^2}$
- $(\mu 2\sigma, \mu + 2\sigma)$ is the approx 95% interval
- $(\mu 3\sigma, \mu + 3\sigma)$ is the approx. 99.7% interval



Gaussian (Normal) Distribution



Gaussian (Normal) Distribution

why Gaussian distribution is the most widely used in statistics?

- **1** easy to interpret: just two parameters $\theta = (\mu, \sigma^2)$
- 2 central limit theorem: the sum of independent random variables has an approximately Gaussian distribution
- **1** least number of assumptions (maximum entropy) subject to constraints of having mean = μ and variance = σ^2
- simple mathematical form, easy to manipulate and implement

homework: show that

$$\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2} dx = 1$$

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 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
 - Joint Probability Distributions
 - Joint CDF and PDF
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 - Conditional PDF and Independence
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Degenerate PDFs

- X is a continuous RV with values $x \in \mathbb{R}$
- ullet consider a Gaussian distribution with $\sigma^2 o 0$

$$\delta(x-\mu) \triangleq \lim_{\sigma^2 \to 0} \mathcal{N}(x|\mu, \sigma^2)$$

• $\delta(x)$ is the **Dirac delta function**, with

$$\delta(x) = \begin{cases} \infty & \text{if } x = 0\\ 0 & \text{if } x \neq 0 \end{cases}$$

• one has $\int\limits_{-\infty}^{\infty}\delta(x)dx=1$

 $(\lim_{\sigma^2 o 0} \int\limits_{-\infty}^{\infty} \mathcal{N}(x|\mu,\sigma^2) dx = 1)$

sifting property

$$\int_{-\infty}^{\infty} f(x)\delta(x-\mu)dx = f(\mu)$$



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 - Degenerate PDFs
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 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
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 - Marginal PDF
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Student's t Distribution

- X is a continuous RV with values $x \in \mathbb{R}$
- $X \sim \mathcal{T}(\mu, \sigma^2, \nu)$, i.e. X has a **Student's** t **distribution**

$$\mathcal{T}(x|\mu,\sigma^2,
u) \propto \left[1 + rac{1}{
u} \left(rac{x-\mu}{\sigma}
ight)^2
ight]^{-(rac{
u+1}{2})} \qquad \qquad (= P_X(X=x))$$

- scale parameter $\sigma^2 > 0$
- ullet degrees of freedom u
- ullet mean $\mathbb{E}[X]=\mu$ defined if u>1
- ullet mode μ
- variance $\operatorname{var}[X] = \frac{\nu \sigma^2}{(\nu-2)}$ defined if $\nu > 2$

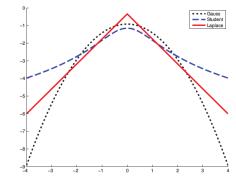
Student's t Distribution

• a comparison of $\mathcal{N}(0,1)$, $\mathcal{T}(0,1,1)$ and Lap $(0,1,\sqrt{2})$

0.8 0.7 0.6 0.5 0.4 0.3 0.1

PDF

log(PDF)

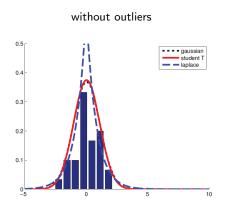


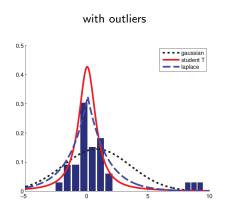
Student's t Distribution

Pros

why should we use the Student distribution?

• it is less sensitive to outliers than the Gaussian distribution





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- 2 Joint Probability Distributions Multivariate
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 - Marginal PDF
 - Conditional PDF and Independence
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 - Correlation and Independence
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Laplace Distribution

- X is a continuous RV with values $x \in \mathbb{R}$
- $X \sim \text{Lap}(\mu, b)$, i.e. X has a Laplace distribution

$$\mathsf{Lap}(x|\mu,b) \triangleq \frac{1}{2b} \mathsf{exp}\bigg(-\frac{|x-\mu|}{b}\bigg) \qquad (= P_X(X=x))$$

- scale parameter b > 0
- mean $\mathbb{E}[X] = \mu$
- ullet mode μ
- variance $var[X] = 2b^2$

compared to Gaussian distribution, Laplace distribution

- is more rubust to outliers (see above)
- ullet puts more probability density at μ (see above)

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 - Gaussian Distribution
 - Degenerate PDFs
 - Student's t Distribution
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 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
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 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
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Gamma Distribution

- X is a continuous RV with values $x \in \mathbb{R}^+$ (x > 0)
- $X \sim Ga(a, b)$, i.e. X has a gamma distribution

$$Ga(x|a,b) \triangleq \frac{b^a}{\Gamma(a)} x^{a-1} e^{-xb}$$
 (= $P_X(X=x)$)

- shape *a* > 0
- rate *b* > 0
- the gamma function is

$$\Gamma(x) \triangleq \int_{-\infty}^{\infty} u^{x-1} e^{-u} du$$

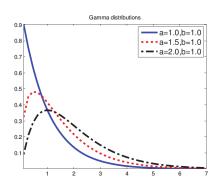
where
$$\Gamma(x)=(x-1)!$$
 for $x\in\mathbb{N}$ and $\Gamma(1)=1$

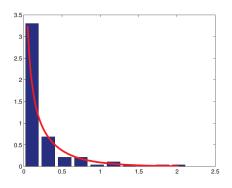
- mean $\mathbb{E}[X] = \frac{a}{b}$
- mode $\frac{a-1}{b}$
- variance $var[X] = \frac{a}{h^2}$

N.B.: there are several distributions which are just special cases of the Gamma (e.g. exponential, Erlang, Chi-squared)

Gamma Distribution

- some Ga(a, b = 1) distributions
- right: an empirical PDF of some rainfall data





Inverse Gamma Distribution

- X is a continuous RV with values $x \in \mathbb{R}^+$
- (x > 0)

- if $X \sim \mathsf{Ga}(a,b)$, i.e. $\frac{1}{X} \sim \mathsf{IG}(a,b)$
- IG(a, b) is the inverse gamma distribution

$$\mathsf{IG}(x|a,b) \triangleq \frac{b^a}{\Gamma(a)} x^{-(a+1)} e^{-b/x} \qquad (= P_X(X=x))$$

• mean $\mathbb{E}[X] = \frac{b}{a-1}$

(defined if a>1)

- mode $\frac{b}{a+1}$
- variance $var[X] = \frac{b^2}{(a-1)^2(a-2)}$

(defined if a > 2)

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- 2 Joint Probability Distributions Multivariate
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 - Marginal PDF
 - Conditional PDF and Independence
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 - Correlation and Independence
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Beta Distribution

- X is a continuous RV with values $x \in [0, 1]$
- $X \sim \text{Beta}(a, b)$, i.e. X has a **beta distribution**

Beta
$$(x|a,b) = \frac{1}{B(a,b)} x^{a-1} (1-x)^{b-1}$$
 $(= P_X(X=x))$

- requirements: a > 0 and b > 0
- the beta function is

$$B(a,b) \triangleq \frac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}$$

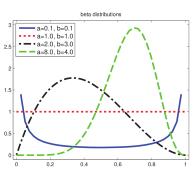
- mean $\mathbb{E}[X] = \frac{a}{a+b}$
- mode $\frac{a-1}{a+b-2}$
- variance $var[X] = \frac{ab}{(a+b)^2(a+b+1)}$

Beta Distribution

beta distribution

Beta
$$(x|a,b) = \frac{1}{B(a,b)} x^{a-1} (1-x)^{b-1}$$
 (= $P_X(X=x)$)

- requirements: a > 0 and b > 0
- if a=b=1 then $\mathsf{Beta}(x|1,1)=\mathit{Unif}(x|1,1)$ in the interval $[0,1]\subset\mathbb{R}$
- this distribution can be used to represent a prior on a probability value to be estimated



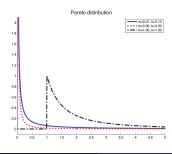
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 - Gaussian Distribution
 - Degenerate PDFs
 - Student's t Distribution
 - Laplace Distribution
 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
 - Joint Probability Distributions
 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
 - Correlation and Independence
 - Common Multivariate Distributions

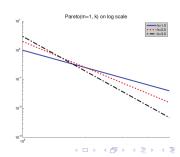
Pareto Distribution

- X is a continuous RV with values $x \in \mathbb{R}^+$ (x > 0)
- $X \sim \text{Pareto}(k, m)$, i.e. X has a **Pareto distribution**

$$\mathsf{Pareto}(x|k,m) = km^k x^{-(k+1)} \mathbb{I}(x \ge m) \qquad (= P_X(X = x))$$

- as $k \to \infty$ the distribution approaches $\delta(x)$
- mean $\mathbb{E}[X] = \frac{km}{k-1}$ (defined for k > 1)
- mode *m*
- variance $var[X] = \frac{m^2 k}{(k-1)^2(k-2)}$
- this distribution is particular useful for its long tail





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 - Degenerate PDFs
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 - Beta Distribution
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 - Conditional PDF and Independence
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Joint Probability Distributions

- consider an ensemble of RVs $X_1, ..., X_D$
- we can define a new RV $\mathbf{X} \triangleq (X_1,...,X_D)^T$
- we are now interested in modeling the stochastic relationship between $X_1,...,X_D$
- in this case $\mathbf{x} = (x_1, ..., x_D)^T \in \mathbb{R}^D$ denotes a particular value (instance) of \mathbf{X}

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 - Degenerate PDFs
 - Student's t Distribution
 - Laplace Distribution
 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
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 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
 - Correlation and Independence
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Joint Cumulative Distribution Function

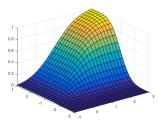
Definition

given a continuous RV ${f X}$ with values ${f x} \in \mathbb{R}^D$

Cumulative Distribution Function (CDF)

$$F(\mathbf{x}) = F(x_1, ..., x_D) \triangleq P_{\mathbf{X}}(\mathbf{X} \leq \mathbf{x}) = P_{\mathbf{X}}(X_1 \leq x_1, ..., X_D \leq x_D)$$

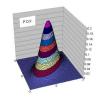
- properties:
 - $0 \le F(x) \le 1$
 - $F(x_1,...,x_j,...,x_D) \le F(x_1,...,x_j + \Delta x_j,...,x_D)$ with $\Delta x_j > 0$
 - $\bullet \ \ \mathsf{lim}_{\Delta x_j \to 0^+} \ F\big(x_1,...,x_j + \Delta x_j,...,x_D\big) = F\big(x_1,...,x_j,...,x_D\big) \quad \ \big(\mathsf{right\text{-}continuity}\big)$
 - $F(-\infty,...,-\infty)=0$
 - $F(+\infty, ..., +\infty) = 1$



Joint Probability Density Function

Definitions

given a continuous RV \mathbf{X} with values $\mathbf{x} \in \mathbb{R}^D$





Probability Density Function (PDF)

$$p(\mathbf{x}) = p(x_1, ..., x_D) \triangleq \frac{\partial^D F}{\partial x_1, ..., \partial x_D}$$

we assume the above partial derivative of F exists

- properties:
 - $F(\mathbf{x}) = P_{\mathbf{X}}(\mathbf{X} \leq \mathbf{x}) = \int_{-\infty}^{x_1} ... \int_{-\infty}^{x_D} \rho(\xi_1, ..., \xi_D) d\xi_1 ... d\xi_D$
 - $P_{\mathbf{X}}(\mathbf{x} < \mathbf{X} \leq \mathbf{x} + d\mathbf{x}) \approx p(\mathbf{x}) dx_1 ... dx_D = p(\mathbf{x}) d\mathbf{x}$
 - $P_{\mathbf{X}}(\mathbf{a} < \mathbf{X} \le \mathbf{b}) = \int_{a_1}^{b_1} ... \int_{a_D}^{b_D} p(\mathbf{x}) dx_1 ... dx_D$

N.B.: p(x) acts as a density in the above computations

Joint Probability Density Function

Definitions

for a discrete RV X we have instead

- Probability Mass Function (PMF): $p(x) \triangleq P_X(X = x)$
- \bullet in the above properties we can remove dx and replace integrals with sums
- the CDF can be defined as

$$F(\mathbf{x}) \triangleq P_{\mathbf{X}}(\mathbf{X} \leq \mathbf{x}) = \sum_{\boldsymbol{\xi}_i \leq \mathbf{x}} p(\boldsymbol{\xi}_i)$$

Joint PDF

Some Properties

reconsider

1
$$F(\mathbf{x}) = P_{\mathbf{x}}(\mathbf{X} \leq \mathbf{x}) = \int_{-\infty}^{x_1} ... \int_{-\infty}^{x_D} p(\xi_1, ..., \xi_D) d\xi_1 ... d\xi_D$$

$$P_{\mathbf{X}}(\mathbf{x} < \mathbf{X} \leq \mathbf{x} + d\mathbf{x}) \approx p(\mathbf{x}) dx_1 ... dx_D = p(\mathbf{x}) d\mathbf{x}$$

- the first implies $\int_{-\infty}^{\infty} ... \int_{-\infty}^{\infty} p(\mathbf{x}) d\mathbf{x} = 1$ (consider $(x_1, ..., x_D) \to (\infty, ..., \infty)$))
- the second implies $p(\mathbf{x}) \geq 0$ for all $\mathbf{x} \in \mathbb{R}^D$
- it is possible that $p(\mathbf{x}) > 1$ for some $\mathbf{x} \in \mathbb{R}^D$

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 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
 - Joint Probability Distributions
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Joint PDF

Marginal PDF

suppose we want the PDF of $\mathbf{Q} \triangleq (X_1, X_2, ..., X_{D-1})^T$ (we don't care about X_D)

- $F_{\mathbf{Q}}(\mathbf{q}) = P_{\mathbf{Q}}(\mathbf{Q} \le \mathbf{q}) = P_{\mathbf{X}}(\mathbf{X} \le (\mathbf{q}, \infty)^T)$ (X_D can take any value in $(-\infty, \infty)$)
- $P_{\mathbf{X}}(\mathbf{X} \leq (\mathbf{q}, \infty)) = \int_{-\infty}^{x_1} ... \int_{-\infty}^{x_{D-1}} \int_{-\infty}^{\infty} p_{\mathbf{X}}(\mathbf{x}) dx_1 ... dx_{D-1} dx_D = \int_{-\infty}^{x_1} ... \int_{-\infty}^{x_{D-1}} \left(\int_{-\infty}^{\infty} p_{\mathbf{X}}(\mathbf{x}) dx_D \right) dx_1 ... dx_{D-1}$
- hence we can define the marginal PDF

$$p_{\mathbf{Q}}(\mathbf{q}) = p_{\mathbf{Q}}(x_1,...,x_{D-1}) \triangleq \int_{-\infty}^{\infty} p_{\mathbf{X}}(x_1,...,x_D) dx_D$$

and one has

$$F_{\mathbf{Q}}(\mathbf{q}) = F_{\mathbf{Q}}(x_1, ..., x_{D-1}) = \int_{-\infty}^{x_1} ... \int_{-\infty}^{x_{D-1}} p_{\mathbf{Q}}(\mathbf{q}) dx_1 ... dx_{D-1}$$

- the above procedure can be also used to marginalize more variables
- the above procedure can be used for obtaining a marginal PMF for discrete variables by removing the dx and replacing integrals with sums, i.e.

$$p_{\mathbf{Q}}(\mathbf{q}) = p_{\mathbf{Q}}(x_1, x_2, ..., x_{D-1}) \triangleq \sum_{x_D} p_{\mathbf{X}}(x_1, x_2, ..., x_D)$$



- 1 Common Continuous Distributions Univariate
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 - Degenerate PDFs
 - Student's t Distribution
 - Laplace Distribution
 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
 - Joint Probability Distributions
 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
 - Correlation and Independence
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Joint PDF

Conditional PDF and Independence

suppose we want the PDF of $\mathbf{Q} \triangleq (X_1, X_2, ..., X_{D-1})^T$ given $X_D = x_D$

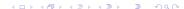
•
$$P_{\mathbf{Q}|X_D}(\mathbf{q} < \mathbf{Q} \le \mathbf{q} + d\mathbf{q} \mid x_D < X_D \le x_D + dx_D) = \frac{P_{\mathbf{X}}(\mathbf{x} < \mathbf{X} \le \mathbf{x} + d\mathbf{x})}{P_{x_D}(x_D < X_D \le x_D + dx_D)}$$

- $P_{\mathbf{X}}(\mathbf{x} < \mathbf{X} \leq \mathbf{x} + d\mathbf{x}) \approx p_{\mathbf{X}}(\mathbf{x}) dx_1 ... dx_D$
- $P_{X_D}(x_D < X_D \le x_D + dx_D) \approx p_{X_D}(x_D) dx_D$
- hence $P_{\mathbf{Q}|X_D}(\mathbf{q} < \mathbf{Q} \le \mathbf{q} + d\mathbf{q} \mid x_D < X_D \le x_D + dx_D) \approx \frac{p_{\mathbf{X}}(\mathbf{x})}{p_{X_D}(x_D)} dx_1...dx_{D-1}$
- we can define the conditional PDF

$$p_{\mathbf{Q}|X_D}(\mathbf{q}|X_D) = p_{\mathbf{Q}|X_D}(X_1, ..., X_{D-1}|X_D) \triangleq \frac{p_{\mathbf{X}}(\mathbf{x})}{p_{X_D}(X_D)}$$

- **Q** and X_D are **independent** $\iff p_{\mathbf{X}}(\mathbf{x}) = p_{\mathbf{Q}}(\mathbf{q})p_{x_D}(x_D)$
- if **Q** and X_D are independent then $p_{\mathbf{Q}|X_D}(\mathbf{q}|x_D) = p_{\mathbf{Q}}(\mathbf{q})$
- the above definitions can be generalized to define the conditional PDF w.r.t. more variables

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 - Degenerate PDFs
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 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
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 - Marginal PDF
 - Conditional PDF and Independence
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 - Correlation and Independence
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Covariance

covariance of two RVs X and Y

$$\operatorname{cov}[X,Y] \triangleq \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y] \qquad (= \operatorname{cov}[Y,X])$$

• if $\mathbf{x} \in \mathbb{R}^d$, the mean value is

$$\mathbb{E}[\mathbf{x}] \triangleq \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} \mathbf{x} p(\mathbf{x}) d\mathbf{x} = \begin{bmatrix} \mathbb{E}[\mathbf{x}_1] \\ \vdots \\ \mathbb{E}[\mathbf{x}_D] \end{bmatrix} \in \mathbb{R}^D$$

• if $x \in \mathbb{R}^d$, the covariance matrix is

$$\mathsf{cov}[\mathbf{x}] \triangleq \mathbb{E}[(\mathbf{x} - \mathbb{E}[\mathbf{x}])(\mathbf{x} - \mathbb{E}[\mathbf{x}])^T] =$$

$$= \begin{bmatrix} \operatorname{var}[X_1] & \operatorname{cov}[X_1, X_2] & \dots & \operatorname{cov}[X_1, X_d] \\ \operatorname{cov}[X_2, X_1] & \operatorname{var}[X_2] & \dots & \operatorname{cov}[X_2, X_d] \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{cov}[X_d, X_1] & \operatorname{cov}[X_d, X_2] & \dots & \operatorname{var}[X_d] \end{bmatrix} \in \mathbb{R}^{D \times D}$$

• N.B.: $cov[x] = cov[x]^T$ and $cov[x] \ge 0$



Correlation

correlation coefficient of two RVs X and Y

$$corr[X, Y] \triangleq \frac{cov[X, Y]}{\sqrt{var[X] \ var[Y]}}$$

it can be to shown that $-1 \le \operatorname{corr}[X, Y] \le 1$

(homework1)

- $\operatorname{corr}[X, Y] = 0 \iff \operatorname{cov}[X, Y] = 0$
- if $\mathbf{x} \in \mathbb{R}^d$ its **correlation** matrix is

$$\mathsf{corr}[\mathbf{x}] \triangleq \begin{bmatrix} \mathsf{corr}[X_1, X_1] & \mathsf{corr}[X_1, X_2] & \dots & \mathsf{corr}[X_1, X_d] \\ \mathsf{corr}[X_2, X_1] & \mathsf{corr}[X_2, X_2] & \dots & \mathsf{corr}[X_2, X_d] \\ \vdots & \vdots & \ddots & \vdots \\ \mathsf{corr}[X_d, X_1] & \mathsf{corr}[X_d, X_2] & \dots & \mathsf{corr}[X_d, X_d] \end{bmatrix} \in \mathbb{R}^{D \times D}$$

• N.B.: $corr[x] = corr[x]^T$

use the fact that $\left(\int f(t)g(t)dt\right)^2 \leq \int f^2dt \int g^2dt$

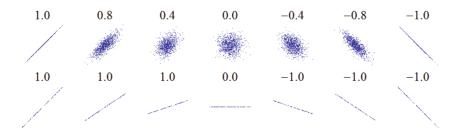
- Common Continuous Distributions Univariate
 - Gaussian Distribution
 - Degenerate PDFs
 - Student's t Distribution
 - Laplace Distribution
 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
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 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
 - Correlation and Independence
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Correlation and Independence

• Property 1: there is a linear relationship between X and Y iff corr[X, Y] = 1, i.e.

$$corr[X, Y] = 1 \iff Y = aX + b$$

• the correlation coefficient represents a degree of linear relationship



Correlation and Independence

• Property 2: if X and Y are independent (p(X, Y) = p(X)p(Y)) then cov[X, Y] = 0 and corr[X, Y] = 0, i.e. (homework)

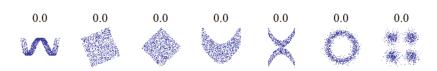
$$X \perp Y \Longrightarrow \operatorname{corr}[X, Y] = 0$$

• Property 3:

$$corr[X, Y] = 0 \Longrightarrow X \perp Y$$

example: with $X \sim U(-1,1)$ and $Y = X^2$ (quadratic dependency) one has corr[X,Y] = 0 (homework)

ullet other examples where $\operatorname{corr}[X,Y]=0$ but there is a cleare dependence between X and Y



a more general measure of dependence is the mutual information

- 1 Common Continuous Distributions Univariate
 - Gaussian Distribution
 - Degenerate PDFs
 - Student's t Distribution
 - Laplace Distribution
 - Gamma Distribution
 - Beta Distribution
 - Pareto Distribution
- 2 Joint Probability Distributions Multivariate
 - Joint Probability Distributions
 - Joint CDF and PDF
 - Marginal PDF
 - Conditional PDF and Independence
 - Covariance and Correlation
 - Correlation and Independence
 - Common Multivariate Distributions

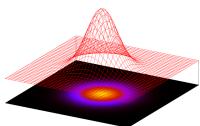


Multivariate Gaussian (Normal) Distribution

- **X** is a continuous RV with values $\mathbf{x} \in \mathbb{R}^D$
- $X \sim \mathcal{N}(\mu, \Sigma)$, i.e. X has a **Multivariate Normal** distribution (MVN) or multivariate Gaussian

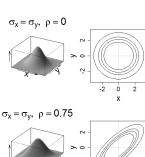
$$\mathcal{N}(\mathbf{x}|oldsymbol{\mu},oldsymbol{\Sigma}) riangleq rac{1}{(2\pi)^{D/2}|oldsymbol{\Sigma}|^{1/2}} \mathsf{exp}igg[-rac{1}{2}(\mathbf{x}-oldsymbol{\mu})^Toldsymbol{\Sigma}^{-1}(\mathbf{x}-oldsymbol{\mu}) igg]$$

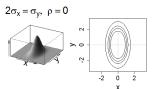
- lacktriangledown mean: $\mathbb{E}[\mathsf{x}] = \mu$
- ullet mode: μ
- ullet covariance matrix: $\mathsf{cov}[\mathbf{x}] = oldsymbol{\Sigma} \in \mathbb{R}^{D imes D}$ where $oldsymbol{\Sigma} = oldsymbol{\Sigma}^T$ and $oldsymbol{\Sigma} \geq 0$
- precision matrix: $\mathbf{\Lambda} \triangleq \mathbf{\Sigma}^{-1}$
- spherical isotropic covariance with $\Sigma = \sigma^2 \mathbf{I}_D$

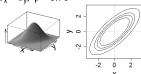


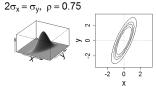
Multivariate Gaussian (Normal) Distribution

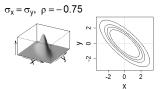
Bivariate Normal

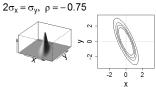












Multivariate Student t Distribution

- **X** is a continuous RV with values $\mathbf{x} \in \mathbb{R}^D$
- ullet X $\sim \mathcal{T}(\mu, \Sigma,
 u)$, i.e. X has a Multivariate Student t distribution

$$\mathcal{T}(\mathbf{x}|\boldsymbol{\mu},\boldsymbol{\Sigma},\nu) \triangleq \frac{\Gamma(\nu/2+D/2)}{\Gamma(\nu/2)} \frac{|\boldsymbol{\Sigma}|^{-1/2}}{\nu^{D/2}\pi^{D/2}} \left[1 + \frac{1}{\nu}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})\right]^{-(\frac{\nu+D}{2})}$$

- lacktriangledown mean: $\mathbb{E}[\mathsf{x}] = \mu$
- lacksquare mode: μ
- $oldsymbol{\Sigma} = oldsymbol{\Sigma}^T$ is now called the scale matrix
- covariance matrix: $\operatorname{cov}[\mathbf{x}] = \frac{\nu}{\nu-2} \mathbf{\Sigma}$
- N.B.: this distribution is similar to MVN but it's more robust w.r.t outliers due to
 its fatter tails (see the previous slides about univariate Student t distribution)

Dirichlet Distribution

- ullet X is a continuous RV with values ${f x} \in \mathcal{S}_{\mathcal{K}}$
- probability simplex $S_K \triangleq \{\mathbf{x} \in \mathbb{R}^K : 0 \le x_i \le 1, \sum_{i=1}^K x_i = 1\}$



- ullet the vector ${f x}=(x_1,...,x_K)$ can be used to represent a set of K probabilities
- $X \sim Dir(\alpha)$, i.e. X has a **Dirichlet** distribution

$$\mathsf{Dir}(\mathbf{x}|\boldsymbol{\alpha}) \triangleq \frac{1}{B(\boldsymbol{\alpha})} \prod_{i=1}^K x_i^{\alpha_i - 1} \mathbb{I}(\mathbf{x} \in S_K)$$

where $lpha \in \mathbb{R}^K$ and B(lpha) is a generalization of the beta function to K variables 2

$$B(\alpha) = B(\alpha_1, ..., \alpha_K) \triangleq \frac{\prod_{i=1}^K \Gamma(\alpha_i)}{\Gamma(\alpha_0)}$$

- $\alpha_0 = \sum_{i=1}^K \alpha_i$
- $\mathbb{E}[x_k] = \frac{\alpha_k}{\alpha_0}$, $\mathsf{mode}[x_k] = \frac{\alpha_k 1}{\alpha_0 K}$, $\mathsf{var}[x_k] = \frac{\alpha_k(\alpha_0 \alpha_K)}{\alpha_0^2(\alpha_0 + 1)}$
- N.B.: this distribution is a multivariate generalization of the beta distribution

²see the slide about the gamma distribution for the definition of $\Gamma(\alpha)$

Credits

Kevin Murphy's book